



DEFORMATION OF SURFACES IN RIEMANNIAN 5-SPACES

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ABSTRACT

Let $M: D \rightarrow V^5$ and $\bar{M}: D \rightarrow \bar{V}^5$ ($D \subset \mathbb{R}^2$) be two surfaces in the second order deformation in the Riemannian 5-spaces V^5 and \bar{V}^5 of curvatures R, \bar{R} respectively.

Let $L: T_m(V^5) \rightarrow T_m(\bar{V}^5)$ be an isometry such that $L\left(\frac{dm}{dt}\right) = \frac{d\bar{m}}{dt}$,

$\pi: T_m(V^5) \rightarrow n = \{v_5\}$. Then M and \bar{M} are in the third order deformation provided that:

- 1- The Gaussian curvature K and the curvature k of the normal bundle satisfies $K^2 - k^2 \neq 0$ on M .
- 2- $\dim T_m^2(M) = 4$ on M .
- 3- M has no non-trivial real conjugate directions at each of its points
- 4- $L\{R(x,y)z\} = \bar{R}(Lx, Ly)Lz$, and $L\{\pi R(x,y)u\} = \bar{\pi}\bar{R}(Lx, Ly)Lu$ for each $x, y, z \in T_m(M)$, $u \in N_m(M) = \{v_3, v_4\}$
- 5- M and \bar{M} are in the third order deformation on ∂D .



INTRODUCTION

The conditions for two isometric surfaces to be in the second order deformation was discussed by A. Švec [3]. His result concerns two infinitesimal isometric surfaces. He obtained the conditions for two infinitesimal isometric surfaces in E^3 to have the same second fundamental forms, that is the variation of the second fundamental form $\delta II = 0$.

Talaat [4] generalized Švec's result from the infinitesimal isometric surfaces to the more general isometric surfaces in the Riemannian 3-spaces.

The aim of this paper is to find the conditions for two surfaces in Riemannian 5-spaces in the second order deformation to be in the third order deformation.



DEFORMATION OF SURFACES

Let V^5 be a 5-dimensional Riemannian space, $D \subset \mathbb{R}^2$ be a bounded domain. Suppose $M: D \rightarrow V^5$ is a surface such that at each point $m \in M$ the dimension of the osculating space $T_m^2(M)$ is equal to 4. To each $m \in M$, associate a frame such that $\{m, v_1, v_2\}$ is the tangent plane $T_m(M)$ and $\{m, v_1, \dots, v_4\}$ is the osculating space. Hence we can write

$$\left. \begin{aligned} dm &= \omega^1 v_1 + \omega^2 v_2, & \omega^3 &= \omega^4 = \omega^5 = 0, \\ dv_1 &= \omega_1^2 v_2 + \omega_1^3 v_3 + \omega_1^4 v_4, & \omega_1^5 &= 0, \\ dv_2 &= -\omega_2^1 v_1 + \omega_2^3 v_3 + \omega_2^4 v_4, & \omega_2^5 &= 0. \end{aligned} \right\} \quad (1)$$

By exterior differentiation of $\omega^3 = \omega^4 = 0$, and applying Cartan's lemma we get

$$\left. \begin{aligned} \omega_1^3 &= a^3 \omega^1 + b^3 \omega^2, & \omega_1^4 &= a^4 \omega^1 + b^4 \omega^2, \\ \omega_2^3 &= b^3 \omega^1 + c^3 \omega^2, & \omega_2^4 &= b^4 \omega^1 + c^4 \omega^2, \end{aligned} \right\} \quad (2)$$

From (1) and (2) we see that

$$\begin{aligned} dv_1 &= \omega_1^2 v_2 + \omega^1 (a^3 v_3 + a^4 v_4) + \omega^2 (b^3 v_3 + b^4 v_4), \\ dv_2 &= -\omega_2^1 v_1 + \omega^1 (b^3 v_3 + b^4 v_4) + \omega^2 (c^3 v_3 + c^4 v_4). \end{aligned}$$

The osculating space $T_m^2(M)$ at each point $m \in M$ is generated by the vectors

$$v_1, v_2, a^3 v_3 + a^4 v_4, b^3 v_3 + b^4 v_4, c^3 v_3 + c^4 v_4. \quad (3)$$

Hence

$$\dim T_m^2(M) = 4 \iff \text{Rank} \begin{pmatrix} a^3 & b^3 & c^3 \\ a^4 & b^4 & c^4 \end{pmatrix} = 2. \quad (4)$$

Let V, W be two tangent vector fields on M such that

$$V = x v_1 + y v_2, \quad W = \xi v_1 + \eta v_2, \quad (5)$$

From (1), (2) and (5)

$$\begin{aligned} WV_m &= W(x v_1 + y v_2) = Wx v_1 + Wy v_2 + x W v_1 + y W v_2 \\ &= Wx v_1 + Wy v_2 + x dv_1(W) + y dv_2(W), \end{aligned}$$



From which we get

$$WV_m = \left\{ \begin{aligned} & \left\{ W_x - y\omega_1^2(W) \right\} v_1 + \left\{ W_y + x\omega_1^2(W) \right\} v_2 + \\ & + (a^3x\xi + b^3y\eta + b^3y\xi + c^3y\eta)v_3 + (a^4x\xi + b^4x\eta + b^4y\xi + c^4y\eta)v_4 \end{aligned} \right\} \quad (6)$$

which shows that the vector $WV_m \in T_m^2(M)$.

Definition: The vector field V is called conjugate if there is another tangent vector field $W \neq 0$, such that WV is a tangent vector field. Equation (6) leads to the following lemma

Lemma: The tangent vector field $V = xv_1 + yv_2$ is conjugate iff

$$(a^3b^4 - a^4b^3)x^2 + (a^3c^4 - a^4c^3)xy + (b^3c^4 - b^4c^3)y^2 = 0. \quad (7)$$

Let $\bar{M}:D \rightarrow \bar{V}^5$ be another surface isometric to M . If $L:T_m(V^5) \rightarrow T_m(\bar{V}^5)$ is the isometry, we may choose the frames of M and \bar{M} in such a way that

$$L\bar{m} = \bar{m}, \quad L v_i = \bar{v}_i \quad \text{and} \quad L dm = d\bar{m}, \quad (8)$$

Then

$$\omega^1 = \bar{\omega}^1, \quad \omega^2 = \bar{\omega}^2, \quad \omega_1^2 = \bar{\omega}_1^2. \quad (9)$$

From (9)

$$\left. \begin{aligned} d\bar{m} &= \omega^1 \bar{v}_1 + \omega^2 \bar{v}_2, \quad \bar{\omega}^3 = \bar{\omega}^4 = \bar{\omega}^5 = 0, \\ d\bar{v}_1 &= \omega_1^2 \bar{v}_2 + \bar{\omega}_1^3 \bar{v}_3 + \bar{\omega}_1^4 \bar{v}_4, \quad \bar{\omega}_1^5 = 0, \\ d\bar{v}_2 &= -\omega_1^2 \bar{v}_1 + \bar{\omega}_2^3 \bar{v}_3 + \bar{\omega}_2^4 \bar{v}_4, \quad \bar{\omega}_2^5 = 0. \end{aligned} \right\} \quad (10)$$

Taking a general curve $\mathcal{J} = \mathcal{J}^{\wedge}(u,v)$, $u = u(t)$, $v = v(t)$ in D , then the corresponding curves on M and \bar{M} are given respectively by

$$M(\mathcal{J}^{\wedge}(t)) = m(u(t), v(t)), \quad \bar{M}(\mathcal{J}^{\wedge}(t)) = \bar{m}(u(t), v(t)),$$

Therefore

$$\left. \begin{aligned} \frac{dm}{dt} &= m_u u' + m_v v' \\ \frac{d^2m}{dt^2} &= m_{uu} (u')^2 + 2m_{uv} u'v' + m_{vv} (v')^2 + m_u u'' + m_v v'' \end{aligned} \right\} \quad (11)$$

Let

$$\omega^k = A^k du + B^k dv, \quad \omega_i^j = C_i^j du + D_i^j dv, \quad K=1,2, \quad i=1,\dots,4 \quad j=1,\dots,5.$$

Then



$$dm = m_u du + m_v dv = \omega^1 v_1 + \omega^2 v_2 = (A^1 v_1 + A^2 v_2) du + (B^1 v_1 + B^2 v_2) dv,$$

which gives

$$m_u = A^1 v_1 + A^2 v_2, \quad m_v = B^1 v_1 + B^2 v_2. \quad (12)$$

From (1) and (12)

$$\left. \begin{aligned} m_{uu} &= A^1_{u1} v_1 + A^2_{u2} v_2 + A^1 (C^2_{12} v_2 + C^3_{13} v_3 + C^4_{14} v_4) + A^2 (-C^2_{11} v_1 + C^3_{23} v_3 + C^4_{24} v_4), \\ m_{uv} &= A^1_{v1} v_1 + A^2_{v2} v_2 + A^1 (D^2_{12} v_2 + D^3_{13} v_3 + D^4_{14} v_4) + A^2 (-D^2_{11} v_1 + D^3_{23} v_3 + D^4_{24} v_4), \\ &= B^1_{u1} v_1 + B^2_{u2} v_2 + B^1 (C^2_{12} v_2 + C^3_{13} v_3 + C^4_{14} v_4) + B^2 (-C^2_{11} v_1 + C^3_{23} v_3 + C^4_{24} v_4), \\ m_{vv} &= B^1_{v1} v_1 + B^2_{v2} v_2 + B^1 (D^2_{12} v_2 + D^3_{13} v_3 + D^4_{14} v_4) + B^2 (-D^2_{11} v_1 + D^3_{23} v_3 + D^4_{24} v_4). \end{aligned} \right\} (13)$$

For the second surface \bar{M} and its curve $\bar{M}(\gamma^i(t))$, we get by the same procedure $\frac{d\bar{m}}{dt}, \frac{d^2\bar{m}}{dt^2}$,

where:

$$\bar{\omega}^k = \omega^k = A^k du + B^k dv, \quad \bar{\omega}^j = \bar{C}^j_i du + \bar{D}^j_i dv, \quad K=1,2, i=1,\dots,4, j=2,\dots,5.$$

Now, introducing

$$\psi^k = L \left(\frac{d^k m}{dt^k} \right) - \frac{d^k \bar{m}}{dt^k}, \quad (14)$$

we give the following definition.

Definition: The two surfaces M and \bar{M} are said to be in k^{th} order deformation; if and only if $\psi^k = 0$.

Let the two surfaces M and \bar{M} be in a second order deformation, hence

$$\psi^2 = L \left(\frac{d^2 m}{dt^2} \right) - \frac{d^2 \bar{m}}{dt^2} = 0, \quad \text{from which we obtain,}$$

$$\sum_{i=1}^2 A^i (C^j_i - \bar{C}^j_i) = 0, \quad \sum_{i=1}^2 A^i (D^j_i - \bar{D}^j_i) = 0, \quad \sum_{i=1}^2 B^i (D^j_i - \bar{D}^j_i) = 0, \quad j=3,4. \quad (15)$$

Since the two tangents m_u and m_v are independent, we get from (12)

$$\begin{vmatrix} A^1 & A^2 \\ B^1 & B^2 \end{vmatrix} \neq 0. \quad (16)$$



From (15_{2,3}) and (16)

$$D_i^j = \bar{D}_i^j \quad i=1,2, \quad j=3,4. \quad (17)$$

From (17) and comparing the coefficients of v_3 and v_4 of (13_{2,3}) for the surfaces M and \bar{M} we get

$$\sum_{i=1}^2 B^i (C_i^j - \bar{C}_i^j) = 0, \quad j = 3,4 \quad (18)$$

Equations (15₁), (16) and (18) imply that

$$C_i^j = \bar{C}_i^j \quad i=1,2, \quad j = 3,4. \quad (19)$$

Equations (17) and (19) imply that

$$\omega_i^j = \bar{\omega}_i^j \quad i=1,2, \quad j = 3,4. \quad (20)$$

Since the osculating space $T_m^2(M)$ at each point $m \in M$ is generated by the vectors

$$v_1, v_2, C_1^3 v_3 + C_1^4 v_4, D_1^3 v_3 + D_1^4 v_4, C_2^3 v_3 + C_2^4 v_4, D_2^3 v_3 + D_2^4 v_4, \quad (21)$$

then from (21)

$$\dim T_m^2(M) = 4 \iff \text{Rank} \begin{pmatrix} C_1^3 & C_2^3 & D_1^3 & D_2^3 \\ C_1^4 & C_2^4 & D_1^4 & D_2^4 \end{pmatrix} = 2 \quad (22)$$

From (11)

$$\begin{aligned} \frac{d^3 m}{dt^3} &= m_{uuu} (u')^3 + 3m_{uuv} (u')^2 v' + 3m_{uvv} u' (v')^2 + m_{vvv} (v')^3 + 3m_{uu} u'' u' + \\ &+ 3m_{uv} (u' v'' + u'' v') + 3m_{vv} v' v'' + m_u u''' + m_v v'''. \end{aligned} \quad (23)$$

Differentiating each equation of (13) with respect to u, v respectively, considering that the two surfaces M and \bar{M} are in a third order deformation, and equating the coefficients of \bar{v}_3, \bar{v}_4 and \bar{v}_5 in

$$\psi^3 = L \left(\frac{d^3 m}{dt^3} \right) - \frac{d^3 \bar{m}}{dt^3} = 0, \text{ we get}$$



$$\left. \begin{aligned}
 D_i^j (C_3^4 - \bar{C}_3^4) &= 0, & C_i^j (C_3^4 - \bar{C}_3^4) &= 0, & C_i^j (D_3^4 - \bar{D}_3^4) &= 0, & D_i^j (D_3^4 - \bar{D}_3^4) &= 0, & i=1,2, j=3,4. \\
 C_i^3 (C_3^5 - \bar{C}_3^5) + C_i^4 (C_4^5 - \bar{C}_4^5) &= 0, & D_i^3 (C_3^5 - \bar{C}_3^5) + D_i^4 (C_4^5 - \bar{C}_4^5) &= 0, \\
 C_i^3 (D_3^5 - \bar{D}_3^5) + C_i^4 (D_3^5 - \bar{D}_3^5) &= 0, & D_i^3 (D_3^5 - \bar{D}_3^5) + D_i^4 (D_4^5 - \bar{D}_4^5) &= 0.
 \end{aligned} \right\} (24)$$

From (22) it follows that

$$\omega_i^j = \bar{\omega}_i^j \quad i=3,4, \quad j=4,5. \quad (25)$$

Now, let $M \subset V^5$ and $\bar{M} \subset \bar{V}^5$ be two surfaces in a second order deformation. Then the structure equations of M and \bar{M} are given respectively by:

$$\left. \begin{aligned}
 d\omega_i^j &= \omega_i^k \wedge \omega_k^j - \frac{1}{2} R_{ikl}^j \omega^k \wedge \omega^l, & R_{ikl}^j + R_{ilk}^j &= 0, \\
 d\bar{\omega}_i^j &= \bar{\omega}_i^k \wedge \bar{\omega}_k^j - \frac{1}{2} \bar{R}_{ikl}^j \bar{\omega}^k \wedge \bar{\omega}^l, & \bar{R}_{ikl}^j + \bar{R}_{ilk}^j &= 0.
 \end{aligned} \right\} (26)$$

Let

$$\bar{\omega}_i^j = \omega_i^j + \tau_i^j. \quad (27)$$

From (9), (20), (26) and (27) we get

$$\left. \begin{aligned}
 \omega_1^4 \wedge \tau_3^4 &= (R_{112}^3 - \bar{R}_{112}^3) \omega^1 \wedge \omega^2, & \omega_1^3 \wedge \tau_3^4 &= (\bar{R}_{112}^4 - R_{112}^4) \omega^1 \wedge \omega^2, \\
 \omega_1^3 \wedge \tau_3^5 + \omega_1^4 \wedge \tau_4^5 &= (\bar{R}_{112}^5 - R_{112}^5) \omega^1 \wedge \omega^2, & \omega_2^4 \wedge \tau_3^4 &= (R_{212}^3 - \bar{R}_{212}^3) \omega^1 \wedge \omega^2, \\
 \omega_2^3 \wedge \tau_3^4 &= (\bar{R}_{212}^4 - R_{212}^4) \omega^1 \wedge \omega^2, & \omega_2^3 \wedge \tau_3^5 + \omega_2^4 \wedge \tau_4^5 &= (\bar{R}_{212}^5 - R_{212}^5) \omega^1 \wedge \omega^2,
 \end{aligned} \right\} (28)$$

$$d\tau_3^4 = -\omega_3^5 \wedge \tau_4^5 - \tau_3^5 \wedge \omega_4^5 - \tau_3^4 \wedge \tau_4^5 + (R_{312}^4 - \bar{R}_{312}^4) \omega^1 \wedge \omega^2,$$

$$d\tau_3^5 = \omega_3^4 \wedge \tau_4^5 + \tau_3^4 \wedge \omega_4^5 + \tau_3^5 \wedge \tau_4^5 + (R_{312}^5 - \bar{R}_{312}^5) \omega^1 \wedge \omega^2,$$

$$d\tau_4^5 = -\omega_3^4 \wedge \tau_3^5 - \tau_3^4 \wedge \omega_3^5 - \tau_3^4 \wedge \tau_3^5 + (R_{412}^5 - \bar{R}_{412}^5) \omega^1 \wedge \omega^2.$$

Now let the three vectors $x, y, z \in T_m(M)$ be such that

$$x = x^1 v_1 + x^2 v_2, \quad y = y^1 v_1 + y^2 v_2, \quad z = z^1 v_1 + z^2 v_2, \quad (x^3 = y^3 = z^3 = 0).$$



Then

$$\begin{aligned}
 R(x,y)z &= R_{ijk}^l x^j y^k z^i v_l, & R_{ijk}^l + R_{ljk}^i &= 0 \\
 &= x^1 y^2 z^1 \left(\sum_1^5 R_{112}^l v_l \right) + x^2 y^1 z^1 \left(\sum_1^5 R_{121}^l v_l \right) + \\
 &\quad + x^1 y^2 z^2 \left(\sum_1^5 R_{212}^l v_l \right) + x^2 y^1 z^2 \left(\sum_1^5 R_{221}^l v_l \right).
 \end{aligned} \tag{29}$$

Again let $u \in N_m(M)$, where $N_m(M) = \{v_3, v_4\}$;

then

$$\begin{aligned}
 R(x,y)u &= R_{ijk}^l x^j y^k u^i v_l \\
 &= (R_{312}^l x^1 y^2 u^3 + R_{412}^l x^1 y^2 u^4 + R_{321}^l x^2 y^1 u^3 + R_{421}^l x^2 y^1 u^4) v_l.
 \end{aligned} \tag{30}$$

Let $\pi: T_m(V^5) \rightarrow n = \{v_5\}$, i.e. $\pi(\sum z^i v_i) = z^5 v_5$ is the natural projection, then $\pi R(x,y)u = (R_{312}^5 u^3 + R_{412}^5 u^4)(x^1 y^2 - x^2 y^1) v_5$.

Assume that for every $x, y, z \in T_m(M)$ and $u \in N_m(M)$

$$L[R(x,y)z] = \bar{R}(Lx, Ly)Lz, \quad L[\pi R(x,y)u] = \bar{\pi} \bar{R}(Lx, Ly)Lu. \tag{31}$$

From (29) \rightarrow (31) and comparing the coefficients of $\bar{v}_1, \dots, \bar{v}_5$ we get,

$$\begin{aligned}
 &(R_{112}^2 - \bar{R}_{112}^2)(x^1 y^2 - x^2 y^1) z^2 = 0, \\
 &(R_{112}^1 - \bar{R}_{112}^1)(x^1 y^2 - x^2 y^1) z^1 = 0, \\
 &(x^1 y^2 - x^2 y^1) \left\{ (R_{112}^3 - \bar{R}_{112}^3) z^1 + (R_{212}^3 - \bar{R}_{212}^3) z^2 \right\} = 0, \\
 &(x^1 y^2 - x^2 y^1) \left\{ (R_{112}^4 - \bar{R}_{112}^4) z^1 + (R_{212}^4 - \bar{R}_{212}^4) z^2 \right\} = 0, \\
 &(x^1 y^2 - x^2 y^1) \left\{ (R_{112}^5 - \bar{R}_{112}^5) z^1 + (R_{212}^5 - \bar{R}_{212}^5) z^2 \right\} = 0,
 \end{aligned} \tag{32}$$

which are valid for every $x^1, x^2, y^1, y^2, z^1, z^2$.

From (32) we get

$$R_{ijk}^l = \bar{R}_{ijk}^l \quad i=1, \dots, 4, j, k=1, 2, \quad l=1, \dots, 5. \tag{33}$$



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From (28) and (33)

$$\begin{aligned}
 \omega_1^4 \wedge \tau_3^4 &= 0, & \omega_1^3 \wedge \tau_3^4 &= 0, \\
 \omega_1^3 \wedge \tau_3^5 + \omega_1^4 \wedge \tau_4^5 &= 0, & \omega_2^4 \wedge \tau_3^4 &= 0, \\
 \omega_2^3 \wedge \tau_3^5 + \omega_2^4 \wedge \tau_4^5 &= 0, & \omega_2^3 \wedge \tau_3^4 &= 0, \\
 d\tau_3^4 &= -\omega_3^5 \wedge \tau_4^5 - \tau_3^5 \wedge \omega_4^5 - \tau_3^5 \wedge \tau_4^5 + (R_{312}^4 - \bar{R}_{312}^4) \omega^1 \wedge \omega^2, \\
 d\tau_3^5 &= \omega_3^4 \wedge \tau_4^5 + \tau_3^4 \wedge \omega_4^5 + \tau_3^4 \wedge \tau_4^5, \\
 d\tau_4^5 &= -\omega_3^4 \wedge \tau_3^5 - \tau_3^4 \wedge \omega_3^5 - \tau_3^4 \wedge \tau_3^5.
 \end{aligned}
 \tag{34}$$

Let us write

$$\tau_3^4 = A \omega^1 + B \omega^2, \quad \tau_4^5 = z_1 \omega^1 + z_2 \omega^2, \quad \tau_3^5 = y_1 \omega^1 + y_2 \omega^2. \tag{35}$$

From (2), (34) and (35₁)

$$\begin{aligned}
 a^3 B - b^3 A &= 0, & a^4 B - b^4 A &= 0, \\
 b^3 B - c^3 A &= 0, & b^4 B - c^4 A &= 0
 \end{aligned}
 \tag{36}$$

From (4) and (36)

$$A = B = 0 \implies \tau_3^4 = 0. \tag{37}$$

Thus equation (34) reduces to

$$\begin{aligned}
 \omega_1^3 \wedge \tau_3^5 + \omega_1^4 \wedge \tau_4^5 &= 0, & \omega_2^3 \wedge \tau_3^5 + \omega_2^4 \wedge \tau_4^5 &= 0, \\
 \omega_3^5 \wedge \tau_4^5 + \tau_3^5 \wedge \omega_4^5 + \tau_3^5 \wedge \tau_4^5 &= (R_{312}^4 - \bar{R}_{312}^4) \omega^1 \wedge \omega^2, \\
 d\tau_3^5 &= \omega_3^4 \wedge \tau_4^5, & d\tau_4^5 &= -\omega_3^4 \wedge \tau_3^5.
 \end{aligned}
 \tag{38}$$

From (2), (35_{2,3}) and (38_{1,2})



$$a^4 z_2 - b^4 z_1 + a^3 y_2 - b^3 y_1 = 0, \quad b^4 z_2 - c^4 z_1 + b^3 y_2 - c^3 y_1 = 0 \tag{39}$$

From (35_{2,3}), (38_{4,5}) and Cartan's lemma, there exist functions S_1, \dots, S_6 such that,

$$\left. \begin{aligned} dy_1 - y_2 \omega_1^2 - z_1 \omega_3^4 &= S_1 \omega^1 + S_2 \omega^2, & dz_1 - z_2 \omega_1^2 + y_1 \omega_3^4 &= S_4 \omega^1 + S_5 \omega^2, \\ dy_2 + y_1 \omega_1^2 - z_2 \omega_3^4 &= S_2 \omega^1 + S_3 \omega^2, & dz_2 + z_1 \omega_1^2 + y_2 \omega_3^4 &= S_5 \omega^1 + S_6 \omega^2. \end{aligned} \right\} \tag{40}$$

From (2) and Cartan's lemma, there exist functions $\alpha_1, \dots, \alpha_8$ such that,

$$\left. \begin{aligned} da^3 - 2b^3 \omega_1^2 - a^4 \omega_3^4 &= \alpha_1 \omega^1 + (\alpha_2 - \frac{1}{2} R_{112}^3) \omega^2, \\ db^3 + (a^3 - c^3) \omega_1^2 - b^4 \omega_3^4 &= (\alpha_2 + \frac{1}{2} R_{112}^3) \omega^1 + (\alpha_3 - \frac{1}{2} R_{212}^3) \omega^2, \\ dc^3 + 2b^3 \omega_1^2 - c^4 \omega_3^4 &= (\alpha_3 + \frac{1}{2} R_{212}^3) \omega^1 + \alpha_4 \omega^2, \\ da^4 - 2b^4 \omega_1^2 + a^3 \omega_3^4 &= \alpha_5 \omega^1 + (\alpha_6 - \frac{1}{2} R_{112}^4) \omega^2, \\ db^4 + (a^4 - c^4) \omega_1^2 + b^3 \omega_3^4 &= (\alpha_6 + \frac{1}{2} R_{112}^4) \omega^1 + (\alpha_7 - \frac{1}{2} R_{212}^4) \omega^2, \\ dc^4 + 2b^4 \omega_1^2 + c^3 \omega_3^4 &= (\alpha_7 + \frac{1}{2} R_{212}^4) \omega^1 + \alpha_8 \omega^2. \end{aligned} \right\} \tag{41}$$

Differentiating each equation of (39) and substituting from (40) and (41) we get two homogeneous equations in ω^1 and ω^2 , and hence

$$\left. \begin{aligned} b^3 S_1 - a^3 S_2 + b^4 S_4 - a^4 S_5 &= -(\alpha_2 + \frac{1}{2} R_{112}^3) y_1 + \alpha_1 y_2 - (\alpha_6 + \frac{1}{2} R_{112}^4) z_1 + \alpha_5 z_2, \\ b^3 S_2 - a^3 S_3 + b^4 S_5 - a^4 S_6 &= -(\alpha_3 - \frac{1}{2} R_{212}^3) y_1 + (\alpha_2 - \frac{1}{2} R_{112}^3) y_2 - (\alpha_7 - \frac{1}{2} R_{212}^4) z_1 + \\ &\quad + (\alpha_6 - \frac{1}{2} R_{112}^4) z_2, \\ c^3 S_1 - b^3 S_2 + c^4 S_4 - b^4 S_5 &= -(\alpha_3 + \frac{1}{2} R_{212}^3) y_1 + (\alpha_2 + \frac{1}{2} R_{112}^3) y_2 - (\alpha_7 + \frac{1}{2} R_{212}^4) z_1 + \\ &\quad + (\alpha_6 + \frac{1}{2} R_{112}^4) z_2, \end{aligned} \right\} \tag{42}$$



$$c^3 S_2 - b^3 S_3 + c^4 S_5 - b^4 S_6 = -\alpha_4 y_1 + (\alpha_3 - \frac{1}{2} R_{212}^3) y_2 - \alpha_8 z_1 + (\alpha_7 - \frac{1}{2} R_{212}^4) z_2. \quad (42)$$

On the surface M the Gaussian curvature K and the curvature of the normal bundle k are given respectively by :

$$K = a^3 c^3 - (b^3)^2 + a^4 c^4 - (b^4)^2, \quad k = b^3 (c^4 - a^4) + b^4 (a^3 - c^3). \quad (43)$$

Assuming $K \neq k$ and taking (43) into consideration, certain combinations of (39) lead to,

$$\left. \begin{aligned} (K-k)y_1 &= (b^3 b^4 - a^3 c^4) (y_2 + z_1) + [a^3 b^4 - a^4 b^3 - a^4 c^4 + (b^4)^2] (z_2 - y_1), \\ (K-k)y_2 &= [a^4 c^4 - (b^4)^2 + c^3 b^4 - b^3 c^4] (y_2 + z_1) + (b^3 b^4 - c^3 a^4) (z_2 - y_1), \\ (K-k)z_1 &= [a^4 b^3 - (b^3)^2 - a^3 b^4 + a^3 c^3] (y_2 + z_1) + (a^4 c^3 - b^3 b^4) (z_2 - y_1), \\ (K-k)z_2 &= (b^3 b^4 - a^3 c^4) (y_2 + z_1) + [a^3 c^3 + b^4 c^3 - (b^3)^2 - b^3 c^4] (z_2 - y_1). \end{aligned} \right\} \quad (44)$$

Certain combinations of (42)_{1,3} lead to,

$$\left. \begin{aligned} (K-k)S_2 &= [a^4 c^4 - (b^4)^2 + c^3 b^4 - b^3 c^4] (S_2 + S_4) + (b^3 b^4 - c^3 a^4) (S_5 - S_1) + L_1 (y_2 + z_1) + L_2 (z_2 - y_1), \\ (K-k)S_5 &= (b^3 b^4 - a^3 c^4) (S_2 + S_4) + [a^3 c^3 + b^4 c^3 - (b^3)^2 - b^3 c^4] (S_5 - S_1) + L_3 (y_2 + z_1) + L_4 (z_2 - y_1). \end{aligned} \right\} \quad (45)$$

Certain combinations of (42)_{2,4} lead to,

$$\left. \begin{aligned} (K-k)S_2 &= (b^3 b^4 - a^3 c^4) (S_3 + S_5) + [a^3 b^4 - a^4 b^3 - a^4 c^4 + (b^4)^2] (S_6 - S_2) + L_5 (y_2 + z_1) + L_6 (z_2 - y_1), \\ (K-k)S_5 &= [a^4 b^3 - (b^3)^2 - a^3 b^4 + a^3 c^3] (S_3 + S_5) + (a^4 c^3 - b^3 b^4) (S_6 - S_2) + L_7 (y_2 + z_1) + L_8 (z_2 - y_1). \end{aligned} \right\} \quad (46)$$

From (40)



$$\left. \begin{aligned} d(y_2+z_1)+(y_1-z_2)(\omega_1^2 + \omega_3^4) &= (S_2+S_4)\omega^1+(S_3+S_5)\omega^2, \\ d(y_1-z_2)-(y_2+z_1)(\omega_1^2+\omega_3^4) &= (S_1-S_5)\omega^1 + (S_2-S_6)\omega^2. \end{aligned} \right\} (47)$$

Theorem: Let $M:D \rightarrow V^5$ and $\bar{M}:D \rightarrow \bar{V}^5$ be two surfaces in the second order deformation, where $D \subset R^2$ is a bounded domain and V^5, \bar{V}^5 are two Riemannian spaces. Suppose that :

- 1- $K^2 - k^2 \neq 0$ on M , 2- $\dim T_m^2(M) = 4$ on M ,
- 3- M has no non-trivial real conjugate directions at each its points,
- 4- $L [R(x,y)z] = \bar{R}(Lx,Ly)Lz, L [\pi R(x,y)u] = \bar{\pi}\bar{R}(Lx,Ly)Lu$ for each $x,y,z \in T_m(M)$, $u \in N_m(M)$,
- 5- M and \bar{M} are in the third order deformation on the boundary ∂M .

Then M and \bar{M} are in the third order deformation.

Proof: We can choose in the bounded domain $D \subset R^2$ coordinates u,v such that

$$\omega^1 = r du , \quad \omega^2 = r dv , \quad r=r(u,v). \tag{48}$$

$$\omega_1^2 = F_1\omega^1 + F_2\omega^2 , \quad \omega_3^4 = F_3\omega^1 + F_4\omega^2 \tag{49}$$

From (45₁), (46₁) and (47); similarly from (45₂), (46₂) and (47)

$$\left. \begin{aligned} &(b^3b^4 - c^3a^4) \frac{\partial(y_1-z_2)}{\partial u} + [a^4c^4 - (b^4)^2 + a^4b^3 - a^3b^4] \frac{\partial(y_1-z_2)}{\partial v} + \\ &+ [(b^4)^2 - a^4c^4 + b^3c^4 - c^3b^4] \frac{\partial(y_2+z_1)}{\partial u} + (b^3b^4 - a^3c^4) \frac{\partial(y_2+z_1)}{\partial v} \\ &= f_1(y_1-z_2) + f_2(y_2+z_1), \\ &[a^3c^3 + b^4c^3 - (b^3)^2 - b^3c^4] \frac{\partial(y_1-z_2)}{\partial u} + (b^3b^4 - a^4c^3) \frac{\partial(y_1-z_2)}{\partial v} + \\ &+ (a^3c^4 - b^3b^4) \frac{\partial(y_2+z_1)}{\partial u} + [a^3c^3 - (b^3)^2 + a^4b^3 - a^3b^4] \frac{\partial(y_2+z_1)}{\partial v} = \\ &= f_3(y_1-z_2) + f_4(y_2+z_1) \end{aligned} \right\} (50)$$



The associated quadratic form λ of (50) is

$$\lambda = (k-K) \left[(a^3 b^4 - a^4 b^3) \mu^2 + (a^3 c^4 - a^4 c^3) \mu \nu + (b^3 c^4 - b^4 c^3) \nu^2 \right], \quad (51)$$

λ is definite because of our assumption that $K^2 - k^2 \neq 0$ and that the surface M has no non-trivial real conjugate directions. Hence the system (50) is elliptic.

Now, since M and \bar{M} are in third order deformation at the boundary ∂M , hence from (25) and (27) we have $\gamma_3^5 = \gamma_4^5 = 0$ on the boundary ∂M . Then from (50) and (44) $y_1 = y_2 = z_1 = z_2 = 0$ for every $m \in M$. Hence M and \bar{M} are in the third order deformation which proves the theorem.

Q.E.D.

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